

Analysis 3 Exercise 2

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Outline

1. Serie 1 Review
2. Course Overview
3. Graph, tangent and normal
4. Method of characteristics
5. Examples
6. Tips for Exercise 2

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Gradient, Divergence, Curl and Laplacian

Gradient
(scalar to vector)

$$u(x, y, z)$$

$$\text{Grad}(u) = \nabla u$$

$$= \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} u = \begin{pmatrix} \frac{\partial u}{\partial x} \\ \frac{\partial u}{\partial y} \\ \frac{\partial u}{\partial z} \end{pmatrix}$$

Divergence
(vector to scalar)

$$\begin{pmatrix} u_1(x, y, z) \\ u_2(x, y, z) \\ u_3(x, y, z) \end{pmatrix}$$

$$\text{Div}(\vec{u}) = \nabla \cdot \vec{u}$$

$$= \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} \cdot \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} \\ = \frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial y} + \frac{\partial u_3}{\partial z}$$

Curl
(vector to vector)

$$\begin{pmatrix} u_1(x, y, z) \\ u_2(x, y, z) \\ u_3(x, y, z) \end{pmatrix}$$

$$\text{Curl}(\vec{u}) = \nabla \times \vec{u}$$

$$= \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} \times \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} \\ = \begin{pmatrix} \frac{\partial u_3}{\partial y} - \frac{\partial u_2}{\partial z} \\ \frac{\partial u_1}{\partial z} - \frac{\partial u_3}{\partial x} \\ \frac{\partial u_2}{\partial x} - \frac{\partial u_1}{\partial y} \end{pmatrix}$$

Laplacian
(scalar to scalar)

$$u(x, y, z)$$

$$\Delta u = \nabla^2 u = \nabla \cdot (\nabla u)$$

$$= \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{pmatrix} \cdot \begin{pmatrix} \frac{\partial u}{\partial x} \\ \frac{\partial u}{\partial y} \\ \frac{\partial u}{\partial z} \end{pmatrix} \\ = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2}$$

Serie 1 Review

1. Classification of PDEs

– (c) $(u_{xx} + 1)^3 = x^3 + 2$

2. Solutions to ODEs

3. Nonexistence of solutions

4. Existence of infinite solutions

5. Multiple Choice

- (c) $v := e^u$ & $\Delta u + \nabla u \cdot \nabla u = 0$
– (d) $\operatorname{div}(\nabla(u^2)) = u$

6. Classification of PDEs

– (c) $e^{\Delta u} = u$

7. Solutions to PDEs

$u_{xx} + 1 = \sqrt[3]{x^3 + 2}$ linear (transform)

$$\begin{aligned} u &= \ln(v) \\ \Delta(\ln(v)) + \nabla(\ln(v)) \cdot \nabla(\ln(v)) \\ &= (\ln(v))_{xx} + (\ln(v))_{yy} + (\ln(v))_{xx}^2 + (\ln(v))_{yy}^2 \\ &= \left(\frac{1}{v}\right)_x + \left(\frac{1}{v}\right)_y + \left(\frac{1}{v}\right)^2 + \left(\frac{1}{v}\right)^2 \\ &= \dots \end{aligned}$$

chain rule: $\nabla(u^2) = \nabla u \cdot 2u$

$\Delta u = \ln(u)$ $u_{xx} + u_{yy} = \ln(u)$ Quasilinear

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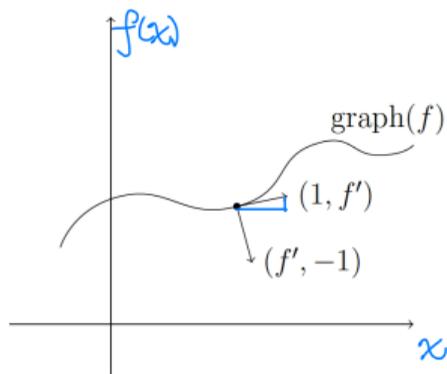
Course Overview

- 1st order PDEs
 - Quasilinear first order PDEs
 - ▶ **Method of characteristics**
 - ▶ Conservation laws
- 2nd order PDEs
 - Hyperbolic PDEs
 - ▶ Wave equation
 - ▶ D'Alembert formula
 - ▶ Separation of variables
 - Parabolic PDEs
 - ▶ Heat equation
 - ▶ Maximum principle
 - ▶ Separation of variables
 - Elliptic PDEs
 - ▶ Laplace equation
 - ▶ Maximum principle
 - ▶ Separation of variables

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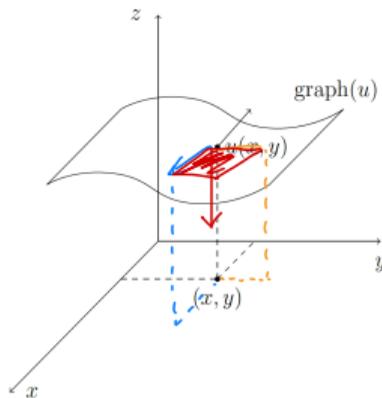
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Graph, tangent and normal



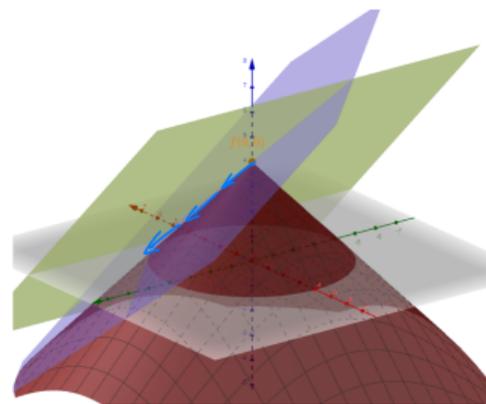
tangent

$$\begin{pmatrix} 1 \\ f' \end{pmatrix} \perp \begin{pmatrix} f' \\ -1 \end{pmatrix}$$



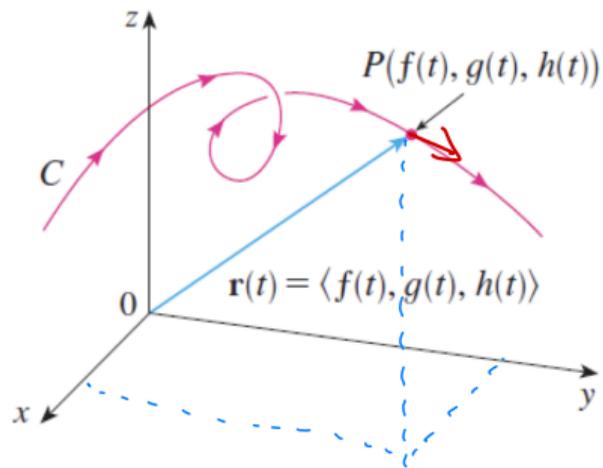
$$\begin{pmatrix} 0 \\ 1 \\ u_y \end{pmatrix} \times \begin{pmatrix} 1 \\ 0 \\ u_x \end{pmatrix} = \begin{pmatrix} u_x \\ u_y \\ -1 \end{pmatrix}$$

↓
downward pointing
normal vector



by "following" the tangent plane,
we "move" on the solution surface.

Parameterize a curve in 3d



at each time t , we need the
 x, y, z positions

if we know $u(x, y)$

$$\vec{r}(t) = \begin{pmatrix} f(t) \\ g(t) \\ u(f(t), g(t)) \end{pmatrix}$$

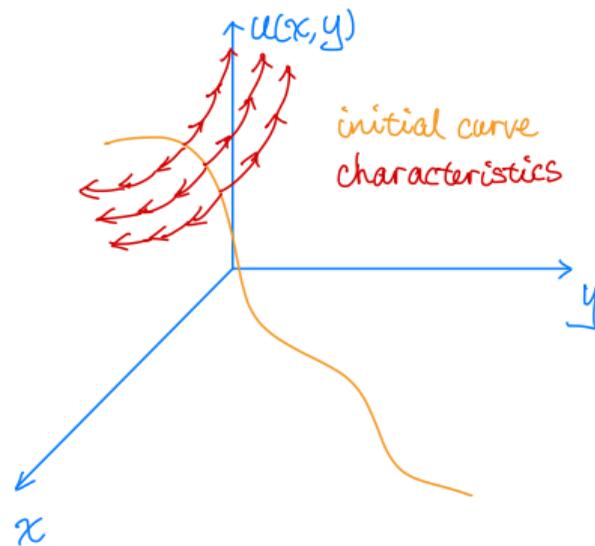
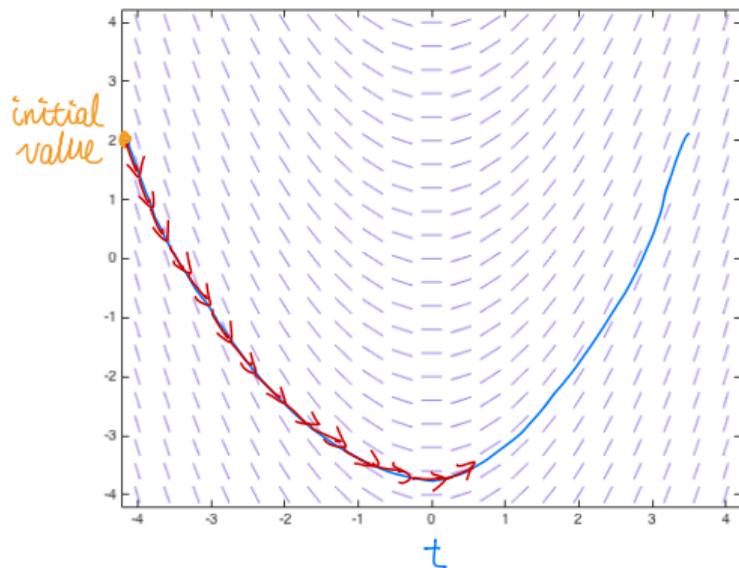
$$\frac{d\vec{r}(t)}{dt} : \underline{\text{velocity / tangent}}$$

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From Vector Field to ODE

$$\dot{y}(t) = f(y, t)$$



First-order Equations

We focus on two-dimensional real-valued function: $u(x, y)$.

General form for the PDE: $F(x, y, u, u_x, u_y) = 0$.

$\text{graph}(u) := (x, y, u(x, y))$ in \mathbb{R}^3

Quasilinear: $a(x, y, u)u_x + b(x, y, u)u_y = c(x, y, u)$

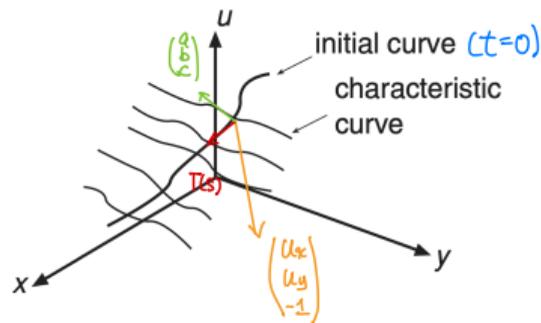
$$\begin{array}{l} \left[\begin{array}{c} a \\ b \\ c \end{array} \right] \cdot \left[\begin{array}{c} u_x \\ u_y \\ -1 \end{array} \right] = 0 \quad \Rightarrow \quad \left. \begin{array}{l} \left[\begin{array}{c} a \\ b \\ c \end{array} \right] \perp \left[\begin{array}{c} u_x \\ u_y \\ -1 \end{array} \right] \\ \left[\begin{array}{c} u_x \\ u_y \\ -1 \end{array} \right] \perp \text{tangent plane} \end{array} \right\} \left[\begin{array}{c} a \\ b \\ c \end{array} \right] \text{ is in the tangent plane} \end{array}$$

Method of characteristics

Results from the last slide:

$\vec{v} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$ is in the tangent plane of $u(x, y)$ and is related to the derivative of the $u(x, y)$.

Goal: find the points $(x; y; u) \in S$, such that $(a(x; y); b(x; y); c(x; y; u)) \in T_{(x; y; u)}S$.



initial curve ($t=0$) parameterized by s .
along the initial curve $t=0$, s changes
along the characteristics, t changes

$$\begin{cases} \frac{dx}{dt} = a \\ \frac{dy}{dt} = b \\ \frac{du}{dt} = c \end{cases}$$

General procedure for Method of characteristics

1. Find a, b, c

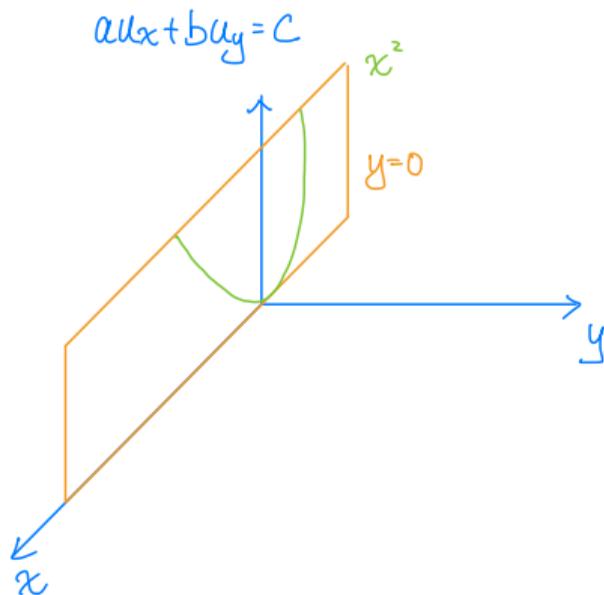
2. Find $\Gamma(s) = \begin{bmatrix} x(0, s) \\ y(0, s) \\ \tilde{u}(0, s) \end{bmatrix}$

i.e. $u(x, 0) = f(x)$ then $\Gamma(s) = \begin{bmatrix} s \\ 0 \\ f(s) \end{bmatrix}$

3.
$$\begin{cases} \frac{d}{dt}x = a, & x_0 = x(0, s) \\ \frac{d}{dt}y = b, & y_0 = y(0, s) \\ \frac{d}{dt}\tilde{u} = c, & \tilde{u}_0 = u(0, s) \end{cases}$$

4. Solve the equations

5. Plug $s(x, y), t(x, y)$ into $\tilde{u}(s, t)$. $\rightarrow u(x, y)$



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Example 1

$$\begin{cases} x^2 u_x - (y^2 + 1) u_y = x^3 u \\ u(1, y) = 2 \end{cases}$$

$$\begin{cases} a = x^2 \\ b = -(y^2 + 1) \\ c = x^3 \tilde{u} \end{cases}$$

$$T(s) = \begin{pmatrix} 1 \\ s \\ 2 \end{pmatrix}$$

$$\begin{cases} \frac{dx}{dt} = x^2 & x(t=0, s) = 1 \\ \frac{dy}{dt} = -y^2 - 1 & y(t=0, s) = s \\ \frac{d\tilde{u}}{dt} = \tilde{u} x^3 & \tilde{u}(t=0, s) = 2 \end{cases}$$

For x :

$$\frac{1}{x^2} dx = 1 dt$$

$$\int \frac{1}{x^2} dx = \int 1 dt$$

$$-\frac{1}{x} = t + C_1(s)$$

$$x = -\frac{1}{t + C_1(s)}$$

$$x(t=0, s) = 1$$

$$-\frac{1}{0 + C_1(s)} = 1 \quad C_1(s) = -1$$

$$x(t, s) = \frac{1}{1-t}$$

For y :

$$\frac{1}{y^2+1} dy = -1 dt$$

$$\int \frac{1}{y^2+1} dy = \int -1 dt$$

$$\arctan(y) = -t + C_2(s)$$

$$y = \tan(-t + C_2(s))$$

$$y(t=0, s) = s$$

$$y(t, s) = \tan(\arctan(s) - t)$$

For \tilde{u} :

$$\frac{d\tilde{u}}{dt} = \tilde{u} x^3 = \tilde{u} \left(\frac{1}{1-t}\right)^3$$

$$\frac{1}{\tilde{u}} d\tilde{u} = \left(\frac{1}{1-t}\right)^3 dt$$

$$\int \frac{1}{\tilde{u}} d\tilde{u} = \int \left(\frac{1}{1-t}\right)^3 dt$$

$$\ln|\tilde{u}| = \frac{1}{2(1-t)^2} + C_3(s)$$

$$\tilde{u} = C_4(s) \exp\left(\frac{1}{2(1-t)^2}\right)$$

$$\tilde{u}(t=0, s) = 2 \quad C_4(s) = 2e^{-\frac{1}{2}}$$

$$\tilde{u}(t, s) = 2e^{-\frac{1}{2}} \exp\left(\frac{1}{2(1-t)^2}\right)$$

$$u(x, y) = \frac{2}{\sqrt{e}} \exp\left(\frac{x^2}{2}\right)$$

(independent of y)

Check:

$$\begin{aligned} x^2 u_x &= x^2 \cdot \frac{2}{\sqrt{e}} \exp\left(\frac{x^2}{2}\right) \cdot x \\ &= \frac{2}{\sqrt{e}} x^3 \exp\left(\frac{x^2}{2}\right) \end{aligned}$$

$$-(y^2+1) u_y = 0$$

$$x^3 u = \frac{2}{\sqrt{e}} x^3 \exp\left(\frac{x^2}{2}\right)$$

$$\begin{cases} x^2 u_x - (y^2+1) u_y = x^3 u \quad \checkmark \\ u(1, y) = \frac{2}{\sqrt{e}} \exp\left(\frac{1}{2}\right) = 2 \quad \checkmark \end{cases}$$

Example 2

$$\begin{cases} u_x + xyu_y = xu \\ u(0, y) = f(y) \end{cases}$$

For x :

$$x_t = 1$$

$$x = t + C_1(s)$$

$$x(t=0, s) = 0 \quad C_1(s) = 0$$

$$x = t$$

$$\begin{cases} a = 1 \\ b = xy \\ c = xu \end{cases}$$

$$T(s) = \begin{pmatrix} 0 \\ s \\ f(s) \end{pmatrix}$$

$$\begin{cases} \frac{dx}{dt} = 1 \\ \frac{dy}{dt} = xy \\ \frac{d\tilde{u}}{dt} = x\tilde{u} \end{cases}$$

$$x(t=0, s) = 0$$

$$y(t=0, s) = s$$

$$\tilde{u}(t=0, s) = f(s)$$

For y :

$$y_t = xy = ty$$

$$\frac{dy}{dt} = ty$$

$$\frac{1}{y} dy = t dt$$

$$\int \frac{1}{y} dy = \int t dt$$

$$\ln|y| = \frac{1}{2}t^2 + C_2(s)$$

$$y = C_2(s) \exp\left(\frac{1}{2}t^2\right)$$

$$y(t=0, s) = s$$

$$y = s \exp\left(\frac{1}{2}t^2\right)$$

For \tilde{u} :

$$u_t = x\tilde{u} = t\tilde{u}$$

same as y

$$\tilde{u}(t, s) = f(s) \exp\left(\frac{1}{2}t^2\right)$$

$$\begin{cases} x = t \\ y = s \exp\left(\frac{1}{2}t^2\right) \end{cases}$$

invert

$$\begin{cases} t = x \\ s = y \exp\left(-\frac{1}{2}x^2\right) \end{cases}$$

$$u(x, y) = f\left(y e^{-\frac{1}{2}x^2}\right) e^{\frac{1}{2}x^2}$$

For example:

$$u(0, y) = f(y) = y^2$$

$$u(x, y) = \left(y e^{-\frac{1}{2}x^2}\right)^2 e^{\frac{1}{2}x^2} = y^2 e^{-x^2} e^{\frac{1}{2}x^2} = y^2 e^{-\frac{1}{2}x^2}$$

check:

$$u_x = y^2 e^{-\frac{1}{2}x^2} \cdot (-x) = -xy^2 e^{-\frac{1}{2}x^2}$$

$$xyu_y = xy \cdot 2y \cdot e^{-\frac{1}{2}x^2} = 2xy^2 e^{-\frac{1}{2}x^2}$$

$$\begin{cases} u_x + xyu_y = xu \quad \checkmark \\ u(0, y) = y^2 e^0 = y^2 \quad \checkmark \end{cases}$$

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Tips for Exercise 2

1. Method of characteristics I

– (c) for y use separation of variables

– (d)
$$\begin{cases} \frac{dx}{dt} = y \\ \frac{dy}{dt} = -x \end{cases}$$

Differentiate again to uncouple the equations.

2. Method of characteristics II

– (b): Is there a way to express t and s in terms of x and y ?

Why is this the case?

Which of the 3 different cases is it according to the lecture note?

3. Multiple Choice

– (c)
$$\left(\frac{f}{g}\right)' = (fg^{-1})' = \frac{f'}{g} - \frac{fg'}{g^2}$$

4. Find a solution

– What is $x^2 + y^2$?

Peers found useful:

1. Method of Characteristics:
Chapters 2.3 and 2.4 of the textbook.

Additional reading:

1. Extra02 on the course website: An example of solution.

References:

1. Lecture notes on the course website.
2. "An Introduction to Partial Differential Equations" by Yehuda Pinchover and Jacob Rubinstein
3. University of Washington Lecture notes