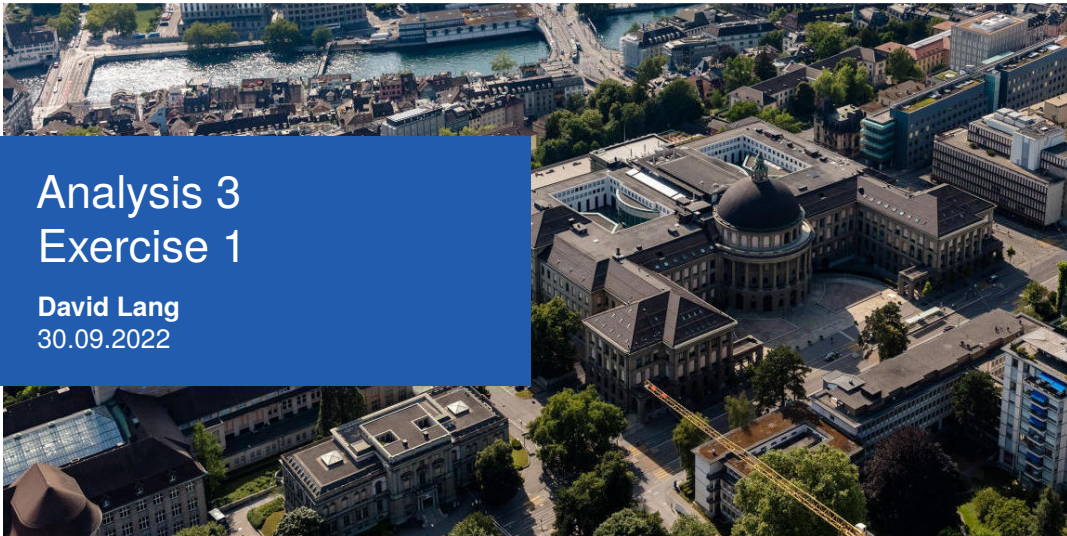


# Analysis 3 Exercise 1

David Lang  
30.09.2022



# Outline

1. Administrative
2. Course Overview
3. Motivation for PDEs
4. ODEs Recap
5. General introduction to PDEs
6. Tips for Exercise 1

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# About Me

Zhenrong Lang (David)  
5th semester at D-ITET.

Exactly one year ago, I took this course and wrote the exam.

I am generally interested in Mathematics, Computer Science and Engineering.

For any questions or suggestions to the exercise session, please reach out under:

`zhlang@student.ethz.ch`

The polybox link for this semester:

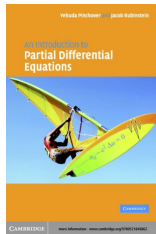
`https://www.polybox.ethz.ch/index.php/s/Elu2hUEoX3pXzgV`

# Course Materials

Course Website:

<https://metaphor.ethz.ch/x/2022/hs/401-0353-00L/>

Additional reading:



There is no bonus for this course.

However, the Series each week are concise and helpful for understanding the materials.

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# Course Overview

- 1st order PDEs
  - Quasilinear first order PDEs
    - ▶ Method of characteristics
    - ▶ Conservation laws
- 2nd order PDEs
  - Hyperbolic PDEs
    - ▶ Wave equation
    - ▶ D'Alembert formula
    - ▶ Separation of variables
  - Parabolic PDEs
    - ▶ Heat equation
    - ▶ Maximum principle
    - ▶ Separation of variables
  - Elliptic PDEs
    - ▶ Laplace equation
    - ▶ Maximum principle
    - ▶ Separation of variables

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# Motivation for PDEs

## Maxwell's Equations

$$\nabla \cdot \vec{D}(\vec{r}, t) = \rho_0(\vec{r}, t)$$

$$\nabla \times \vec{E}(\vec{r}, t) = -\frac{\partial}{\partial t} \vec{B}(\vec{r}, t)$$

$$\nabla \times \vec{H}(\vec{r}, t) = \frac{\partial}{\partial t} \vec{D}(\vec{r}, t) + \vec{j}_0(\vec{r}, t)$$

$$\nabla \cdot \vec{B}(\vec{r}, t) = 0$$

## The Schrödinger Equation

$$\left[-\frac{\hbar^2}{2m} \nabla^2 + V(\vec{x})\right] \Psi(\vec{x}, t) = i\hbar \frac{\partial}{\partial t} \Psi(\vec{x}, t)$$

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# Equations

## Polynomial Equations

$$x^2 - 4x + 3 = 0$$

Solution:

$$x_1 = 1, x_2 = 3$$

## Ordinary Differential Equations

$$\begin{cases} \ddot{y}(t) - \dot{y}(t) - 6y(t) = 0 \\ y(0) = 1 \\ \dot{y}(0) = 2 \end{cases}$$

Solution:

$$y(t) = \frac{1}{5}e^{-2t} + \frac{4}{5}e^{3t}$$

## Partial Differential Equations

$$\begin{cases} u_{tt}(x, t) - c^2 u_{xx}(x, t) = 0 \\ u(x, t = 0) = \sin(x) \\ u_t(x, t = 0) = 0 \end{cases}$$

Solution:

$$u(x, t) = \frac{\sin(x + ct) + \sin(x - ct)}{2}$$

# Definitions for ODEs

## General Definition

$$F(t, x, x', \dots, x^{(n-1)}) = x^{(n)}$$

1. order:

The highest derivative in the equation.

In this case:  $n$ .

2. linear:

$y$  and its derivatives do not appear as powers or in other functions, but always directly as a summand, that is at most multiplied by a factor, i.e. can be written in the following form:

$$x^{(n)}(t) + a_{n-1}(t)x^{(n-1)}(t) + \dots + a_1(t)\dot{x}(t) + a_0(t)x(t) = s(t)$$

3. homogeneous:

$$s(t) = 0$$

4. constant variables

If all the coefficients are constant.

# Ansatz 1: Exponential Ansatz

Illustration via example:  $y''(x) + 2y'(x) + 2y(x) = e^{3x}$

# Ansatz 1: Exponential Function

## Special case

If the characteristic polynomial has the form:  $\lambda^2 + \lambda = 0$ . Then the general solution for the ODE is

$$y(x) = \begin{cases} \alpha \cosh(\sqrt{-\lambda}x) + \beta \sinh(\sqrt{-\lambda}x), & \lambda < 0 \\ \alpha + \beta x, & \lambda = 0 \\ \alpha \cos(\sqrt{\lambda}x) + \beta \sin(\sqrt{\lambda}x), & \lambda > 0 \end{cases}$$

## Ansatz 2: Method of Integrating Factors

Illustration via example:  $x'(t) + \lambda x(t) = 1, x(0) = x_0$ .

## Ansatz 3: Separation of Variables

Illustration via example:  $y'(t) = y^2(t)t + t$



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# General introduction to PDEs

## Definition

A partial differential equation, or PDE, is an equation involving an unknown function of more than one variable and certain of its partial derivatives.

The general form of a PDE for a function  $u(x_1, x_2, \dots, x_n)$  is  $F(x_1, x_2, \dots, u, u_{x_1}, u_{x_2}, \dots, u_{x_{11}}) = 0$

1. Order: highest order partial derivative of the function with respect to any variable.
2. Linearity:
3. Quasi-linearity: linear with respect to the highest order derivative
4. homogeneous: every term that doesn't depend on  $u$  is equal to 0.

# Exercises on classification

1.  $uu_x + x^2u_y = u^3$
2.  $uu_x + u^2u_y + u = e^4$
3.  $u_xu_y = x^2y$
4.  $u_t = u_yu_{xx} + u^2u_{yy} + u_x^2$
5.  $u_{xy}^2 = xu + u_y$
6.  $u_x + u_{tt} + 2u = e^x$
7.  $u_x + u_{tt} + 3uu_x = e^x$
8.  $u_{xx} + u_t^2 + e^u = 0$
9.  $u_{xx}^2 + u_t + e^u = 0$
10.  $u \sin(u_x) + u_{yy} = 0$

# Initial and Boundary Conditions

Why do we need initial and boundary conditions?

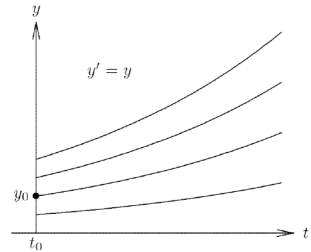
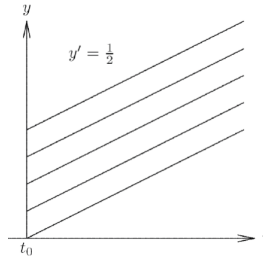
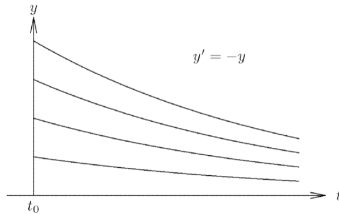
Example:  $u_t = u_{xx}$

Initial Conditions:

Boundary Conditions:

# Well-posed Problem

Existence + Uniqueness + Stability



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# Tips for Exercise 1

1. Classification of PDEs
2. Solutions to ODEs (Important for later)
  - (a): Separation of Variables
  - (b): particular solution or Method of Integrating factors
  - (c): as (b)
  - (d): as (b)
  - (e): as (b)
  - (f): Exponential Ansatz, case studies on  $\lambda$
3. Nonexistence of solutions
  - Try to find  $u_{xy}$  and  $u_{yx}$ . What do you notice?
4. Existence of infinite solutions
  - Try polynomials.
5. Multiple Choice
  - (c) If  $v = e^u$ , how to express  $u$  in terms of  $v$ ?

Peers found useful:

1. Introduction to PDEs:  
3Blue1Brown's Playlist on Differential Equations  
<https://youtube.com/playlist?list=PLZHQObOWTQDNPOjrT6KVIfJuKtYTftqH6>
2. More on ODEs:  
"Ordinary Differential Equations" by Vladimir I. Arnol'd

Additional reading:

1. Chapter 1.5 in the lecture notes: Modelling a stock market

References:

1. Lecture notes on the course website.
2. "An Introduction to Partial Differential Equations" by Yehuda Pinchover and Jacob Rubinstein
3. Princeton University Lecture notes